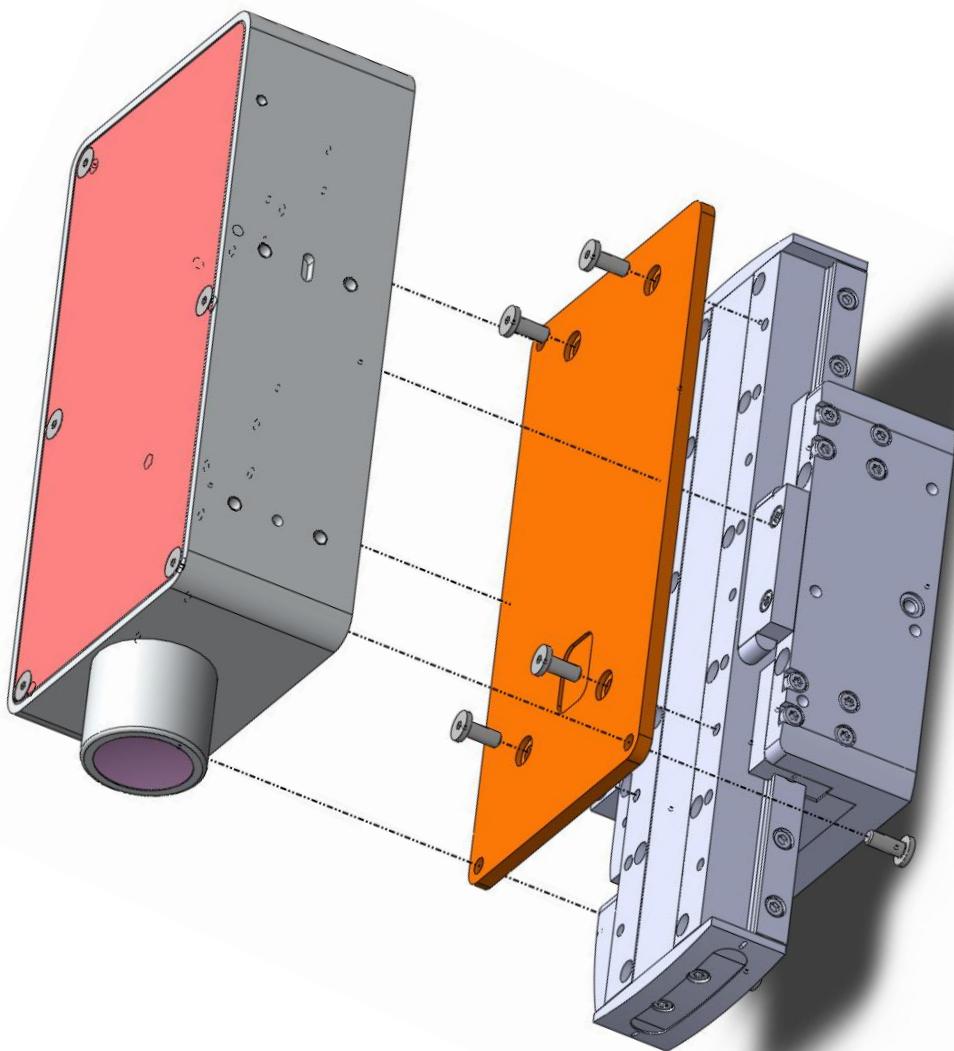


# helInspect™

# H4



# SYSTEMS GUIDE

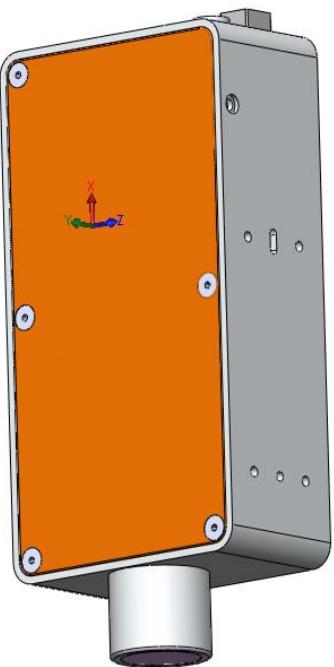
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# (A) Configuration Options

## 1) heliInspect™ H4 - 3D-measurement head

The H4 measurement head is the core component from which high resolution 3D-measurement systems can be built. Complementary hardware options are described on the following pages.

	<p><b>heliInspect™ H4</b></p> <p>3D-measurement head with integrated</p> <ul style="list-style-type: none"> <li>- high-speed 3D-imager <b>heliSens™ S3</b></li> <li>- high-speed camera board B3</li> <li>- imaging optics</li> <li>- Michelson interferometer</li> </ul> <p>The H4 comes with two illumination options:</p> <p><b>H4.2-LED-R040-USB</b></p> <ul style="list-style-type: none"> <li>- power LED with collimation optics</li> </ul> <p><b>H4.2-SLD-R040-USB</b></p> <ul style="list-style-type: none"> <li>- 840 nm SLED with collimation optics</li> <li>- particularly suited for tomographic applications</li> </ul>
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### Performance

2D mode	live-view for navigation on sample (optional)
field of view	11.12 x 11.6 mm (standard configuration)
numerical aperture	0.1 (standard configuration)
working distance	16 mm (standard configuration)
vertical resolution	100 nm standard, 20 nm in phase mode
vertical scan speed	up to 50 mm per second
lateral resolution	40 µm (standard configuration)
reflectivity of sample	< 0.1% to 100%

## 2) Driver Electronics heliDriver™ D1

The heliDriver™ supplies the H4 measurement head with power and serves to condition signals for trigger and position encoders. It can be configured to adapt to various input voltages and signal levels.

	<p><b>heliDriver™ D1.2.2</b></p> <p>features</p> <ul style="list-style-type: none"><li>- voltage controlled power supply for the H4</li><li>- current controlled power supply for H4 power LED / SLD</li><li>- signal conditioning of trigger and AB encoder inputs</li></ul> <p>Note:</p> <p>Please contact Heliotis in case of integration with 3<sup>rd</sup> scanners or motor controllers.</p>
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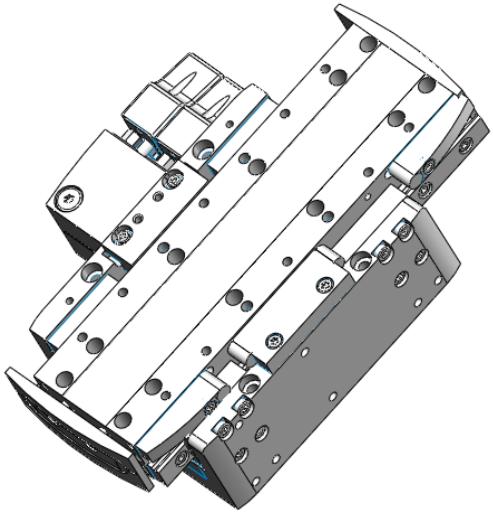
## 3) Scanner

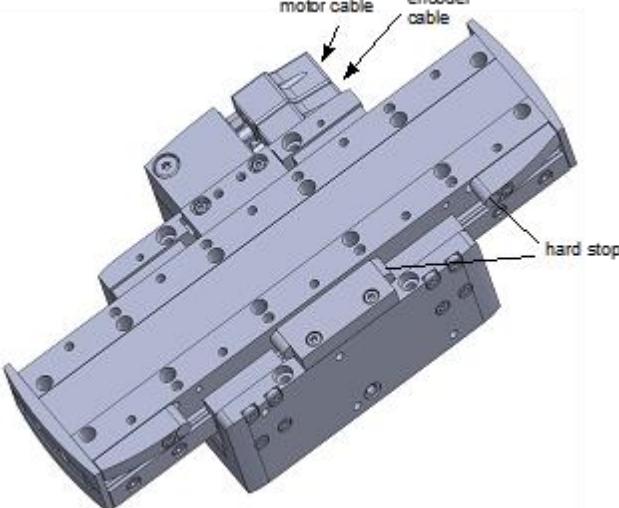
The measurement principle of the heliInspect™ H4 (i.e. scanning white light interferometry) requires a precise axial movement. Heliotis recommends the following precision linear motors with integrated optical encoders. Their long and precise stroke accomplishes positioning and scanning operations in a single unit.

Note that the system performance may be optimized by selecting alternative scanners for a given application. Examples:

- For small height ranges (<500 micrometers) piezo based scanners may result in higher accuracy and shorter measurement times.
- For high accuracy applications scanners with higher resolution and tighter tolerances should be considered.
- Spindle motors with a high resolution measurement system may reduce system cost and complexity.

Please contact Heliotis in case alternative scanner stages should be used. Our engineers can recommend scanners and settings.

	<b>J-Lxu40F60-E01</b> linear motor axis with precise, self-lubrication ball bearing guide, stroke 40 mm, integrated optical measurement system with 100 nm resolution
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	<p><b>J-Lxu80F60-E01</b></p> <p>linear motor axis with precise, self-lubrication ball bearing guide, stroke 80 mm, integrated optical measurement system with 100 nm resolution</p>
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## 4) Axis Controller

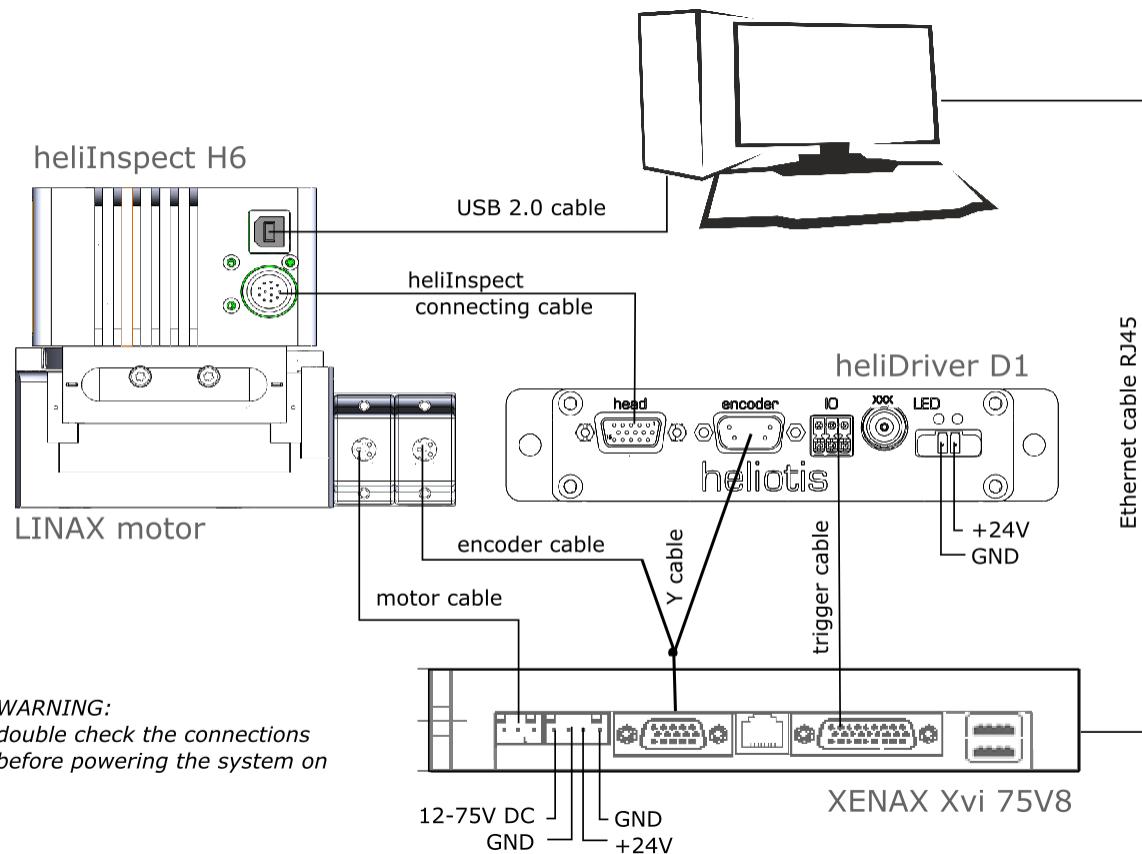
To control the linear motors of the previous section, we recommend the servo controller below. This model is fully supported by the Heliotis' software development kit and software applications.

	<p><b>JXvi-75V8</b></p> <p>servo controller with state-control and observer, S-curves profile generator incl. Web Server, Ethernet TCP/IP, RS232 and 12 Input, 8 Output 24V</p>
	<p><b>JXvi-48V6</b></p> <p>servo controller with state-control and observer, S-curves profile generator incl. Web Server, Ethernet TCP/IP, RS232 and 4 Input, 2 Output 24V LINAX license included.</p>

## 5) Cabling

The heliInspect™ system should be wired as shown below. Cables come in standard length of 1.5 m, 3 m and 5 m. Please contact Heliotis in case of different length requirements.

For compatibility with drag chains the 'high-flex' cables should be chosen.  
Note that the 'trigger cable' comes with the heliDriver™ D1 by default.

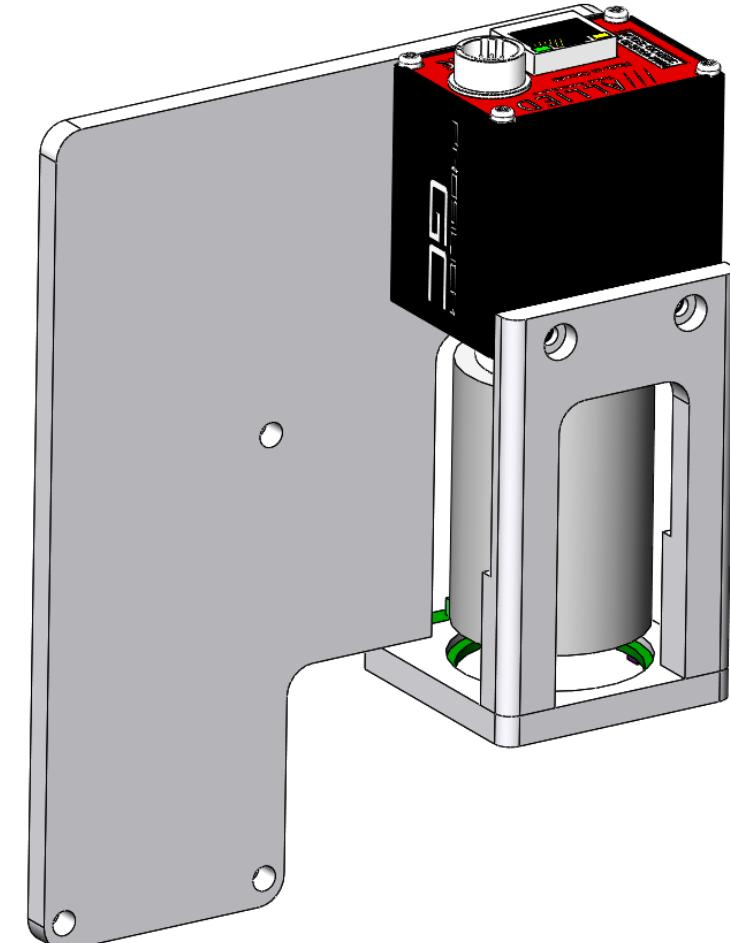


connecting cable heliInspect™  HD D-Sub 15P Male -12x0.14mm2— Hirose HR10-10P-12PA	standard cable HI-CC-L1.5-ST (length 1.5m) HI-CC-L3.0-ST (length 3.0m) HI-CC-L5.0-ST (length 5.0m)  chain-flex cable HI-CC-L1.5-CF (length 1.5m) HI-CC-L3.0-CF (length 3.0m) HI-CC-L5.0-CF (length 5.0m)
motor cable  D-Sub 9 pole ---3x0.75mm2--- Wago 3.5mm	standard cable F-LINAX-CCM-L1.5-ST (length 1.5m) F-LINAX-CCM-L3.0-ST (length 3.0m) F-LINAX CCM-L5.0-ST (length 5.0m)  chain-flex cable F-LINAX-CCM-L1.5-CF (length 1.5m) F-LINAX CCM-L3.0-CF (length 3.0m) F-LINAX CCM-L5.0-CF (length 5.0m)
encoder cable  HD D-Sub 15 pole jack ---12x0.14mm2--- HD D-Sub 15 pole pins	standard cable F-LINAX-CCE-L1.5-ST (length 1.5m) F-LINAX CCE-L3.0-ST (length 3.0m) F-LINAX CCE-L5.0-ST (length 5.0m)  chain-flex cable F-LINAX-CCE-L1.5-CF (length 1.5m) F-LINAX CCE-L3.0-CF (length 3.0m) F-LINAX CCE-L5.0-CF (length 5.0m)
Y-cable for XENAX encoder  1 x 15 pole HD D-Sub male, 1 x 15 pole HD D-Sub female, 1 x D-Sub 9 x pole female, length 0.25m	F-Y-CABLE-D-SUB-L0.5
USB cable, length = 4.5m high-flexibility (compatible with drag chains)	X-USB-L4.5-CF
GigE cable  Length = 5m	X-RJ45-L5-5E

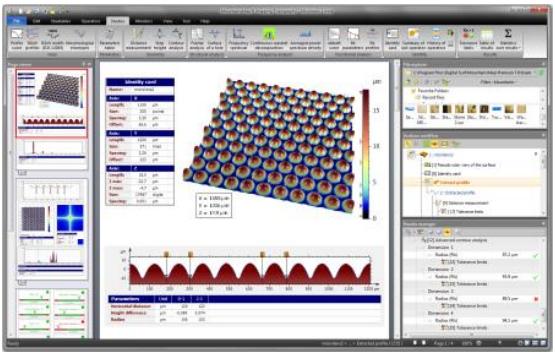
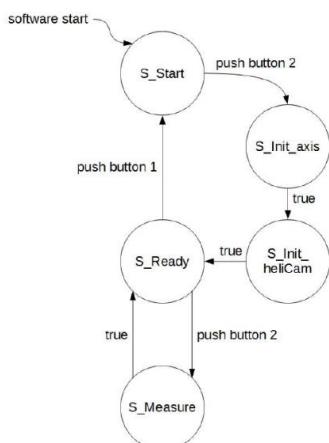
## 6) 2D-Camera-Module

The heliInspect™ H4 can be equipped with a 2D-Camera-Module to aid interactive operation. It consists of an industrial grade GigE camera, a high resolution objective, LED illumination and mounting parts.

The module provides a live view of the sample under test. In conjunction with the application software heliCommander™ the 2D live view can also be used to define the area of interest for 3D measurements and for capturing color images for evaluation and documentation purposes.

	<p><b>PX-2D1.0</b></p> <ul style="list-style-type: none"><li>- industrial grade GigE camera</li><li>- high resolution objective</li><li>- LED ring illumination</li><li>- set of cables</li><li>- mounting bracket</li></ul>
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## 7) Software

	<p><b>heliCommander™ 3.3</b> <b>PX-HC3.3</b></p> <p>Graphical User Interface and application framework supporting</p> <ul style="list-style-type: none"> <li>- 3 axis portal</li> <li>- <b>heliInspect™ 3D-sensors</b></li> <li>- 2D-camera module</li> <li>- interactive operation</li> <li>- automated operation (recipes)</li> <li>- TCP/IP socket interface</li> </ul>
	<p><b>MountainsMap™</b> <b>Imaging Topography</b> <b>DS-MM-TOPO</b></p> <ul style="list-style-type: none"> <li>- comprehensive report generation</li> <li>- large number of operators, e.g. surface parameters ISO 25178 and ISO 4287</li> <li>- WYSIWYG report editor</li> </ul>
 <pre> graph TD     Start((software start)) --&gt; S_Start((S_Start))     S_Start --&gt; S_Init_axis((S_Init_axis))     S_Init_axis -- true --&gt; S_Ready((S_Ready))     S_Ready --&gt; S_Measure((S_Measure))     S_Measure --&gt; S_Start     S_Measure --&gt; S_Init_axis     S_Measure --&gt; S_Ready     S_Ready --&gt; S_Measure     S_Ready -- push button 1 --&gt; S_Start     S_Ready -- push button 2 --&gt; S_Init_axis     S_Init_axis -- push button 2 --&gt; S_Ready     </pre>	<p><b>Software Development Kit</b> <b>heliSDK1.6</b></p> <ul style="list-style-type: none"> <li>- for integration into client applications based on C++, LabVIEW®, Halcon™ or Python</li> <li>- available on Windows and Linux</li> <li>- free of charge</li> </ul>

# (B) Configuration Sheet

Function	Configuration	Selection
3D-measurement head	H4.2-SLD-R040-USB 40 04 01	
	H4.2-LED-R040-USB 40 04 11	
Driver electronics	D1.2.2 40 00 01	x
Scanner	J-Lxu40F60-E0.1 90 01 11	
	J-Lxu80F60-E0.1 90 01 10	
Axis controller	J-Xvi-75V8 90 01 15	
	J-Xvi-48V6 90 01 16	
Connecting cable	HI-CC-L1.5-ST 40 03 65	
	HI-CC-L3.0-ST 40 03 66	
	HI-CC-L5.0-ST 40 03 67	
	HI-CC-L1.5-CF 40 03 60	
	HI-CC-L3.0-CF 40 03 61	
Motor cable	HI-CC-L5.0-CF 40 03 62	
	F-LINAX-CCM-L1.5-ST 90 01 30	
	F-LINAX-CCM-L3.0-ST 90 01 31	
	F-LINAX CCM-L5.0-ST 90 01 32	
	F-LINAX-CCM-L1.5-CF 90 01 35	
	F-LINAX CCM-L3.0-CF 90 01 36	
Encoder cable	F-LINAX CCM-L5.0-CF 90 01 37	
	F-LINAX-CCE-L1.5-ST 90 01 40	
	F-LINAX CCE-L3.0-ST 90 01 41	
	F-LINAX CCE-L5.0-ST 90 01 42	
	F-LINAX-CCE-L1.5-CF 90 01 45	
	F-LINAX CCE-L3.0-CF 90 01 46	
	F-LINAX CCE-L5.0-CF 90 01 47	

<b>Y-cable</b>	F-Y-CABLE-D-SUB-L0.5 90 01 50	
<b>USB cable</b>	X-USB-L4.5-CF 90 00 00	
<b>GigE cable</b>	X-RJ45-L5-5E 90 00 10	
<b>2D-camera module (optional)</b>	PX-2D1.0 50 80 20	
<b>Software</b>	heliCommander3.3 50 90 20	
	heliViewer3.2 50 90 10	X (free)
	heliSDK1.6 50 90 00	X (free)
	DS-MM-TOP0 90 04 00	